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UNITED STATES UTILITY PATENT APPLICATION

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TITLE: UTILITY TRANSPORT SYSTEM

CONFIDENTIAL AND PROPRIETARY DOCUMENT

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I FIELD OF THE INVENTION

This invention relates to removable utility transport systems which will move large heavy objects with precision.

II BACKGROUND OF THE INVENTION

U.S. Patent 5,628,522 discloses a footed cart having normally disengaged wheels. This concept comprises a wheeled cart in which the wheels can be retracted allowing the cart to stand on four legs. When in motion, the wheels are extended and the cart is manually pulled or pushed by means of a handle. It is not designed to move another object, nor is it self-propelled.

III SUMMARY OF THE INVENTION

A. OBJECTS OF THE INVENTION

One object of the present invention is to provide a removable utility transport system which is joystick driven.

Another object of the present invention is to provide a removable utility transport system which will temporarily attach to and move a piece of equipment weighing up to 3,000 pounds.

Another object of the present invention is to provide a removable utility transport system which allows for incremental user controlled movements across various fixed terrains (asphalt, cement, carpeting, vinyl, etc.).

Another object of the present invention is to provide a removable utility transport system which allows the operator to control its speed and function to maneuver around obstacles, negotiate ADA specification ramps and hallways.

Another object of the present invention is to provide a removable utility transport system which allows operators to install and deinstall equipment of their choosing.

B. SUMMARY

The present invention is a utility transport having electro-pneumatic controls for coupling and decoupling of devices which are in weight and sensitivity categories that make manual movement without power assist difficult or impossible.

IV. THE DRAWINGS

Figure 1 is an overall view of the present invention.

Figure 2 is perspective cutaway view of the lower portion of the present invention. Some parts are shown in phantom for clarity.

Figure 3 is a side view of the present invention (some parts not shown for clarity) showing it configured to receive the docking tongue of a device which will be moved.

Figure 4 is a side view of the present invention showing it after the docking tongue is in place.

Figure 5 is a side view of the present invention showing how the docking tongue of the device to be moved is captured.

Figure 6 is a side view of the present invention showing how the invention's drive wheel remains on the floor, with the invention's other wheels and the nearest wheels of the device to be moved lifted from the floor.

V. DESCRIPTION OF PREFERRED EMBODIMENTS

In accordance with the present invention, Figure 1 shows a motorized hand truck assembly 10 comprising a handle 12, a vertical frame 15, a cabinet 17, motor and wheel units 30, rear casters 20, a motion control unit 25 and docking control unit 27. Both control units are commercially available, off-the-shelf components. Vertical frame 15 provides a mounting surface for left hand pushbutton 16 and right hand pushbutton 18.

The first motion control unit 25 comprises joystick 26. The second motion control unit 27 comprises joystick 28. Cabinet 17 houses commercially available rechargeable batteries, air compressor, motor controller, and charging unit (not shown). Control panel 19 comprises commercially available controls and indicators, and provides information to the user regarding the status of the batteries' charge.

In Figure 2, two motor and wheel units 30 comprise a drive wheel 35 and a motor 37, both commercially available. Rear casters 20 provide stability for the device when it is standing alone. Air bag 40 provides force to close hitch 59, as well as lifting the truck assembly 10.

In Figure 3, the top portion of air bag 40 is mounted to upper air bag mounting frame 45 by means of fasteners 41. The lower portion of air bag 40 is mounted to lower air bag mounting frame 47 by means of fasteners 42. Arm 49 is attached to lower air bag mounting frame 47 by nut and bolt combination 84 and pivots at lower frame 57 by means of nut and bolt combination 86.

Hitch 59 is attached to arm 49 via linkage 80 and nuts and bolt combination 82. Since air bag 40 is deflated, lower air bag mounting frame 47 is in the open position. Since hitch 59 is attached to lower air bag mounting frame 47 as previously described, it is also in the open position, providing an opening for receiver 60.

When receiver 60 comes into contact with sensor 50 (shown disengaged), sensor 50 will signal that receiver 60 is fully in place.

In Figure 4, receiver 60 is attached to the device to be moved by means of nuts 108, bolts 107, and washers 109, and is shown generally at 100. Receiver 60 is shown fully inserted into lower frame 43. All wheels 20, 35, and 105 are resting on floor 110.

In Figure 5, air bag 40 is partially inflated due to sensor 50 having signaled that receiver 60 is fully in place. Air bag 40 pushes lower air bag mounting frame 47 down, causing arm 49 to rotate downward, pushing linkage 80, which in turn pushes hitch 59 into its fully closed position. Latch pin 70 captures hole 65, preventing receiver 60 from coming out of lower frame and hitch 55. Sensor 50 is shown fully engaged.

In Figure 6, air bag 40 is fully inflated by means of actuating left hand push button 16. Since hitch 59 is already fully closed, the additional inflation of air bag 40 pushes lower frame 57 down, keeping drive wheels 35 on floor 110, but raising the remainder of the assembly. Rear casters 20 and wheels 105 are now free of the floor allowing device 100 to be moved.

Actuating joystick 28 on second motion control unit 27 delivers electrical power from the batteries (not shown) to motors 37 (Fig.2). Depending on the position of joystick 28, more electrical power may be delivered to one motor than the other, causing assembly 10 to turn. Moving joystick 28 more fully increases the electrical power to motors 37, causing assembly 10 to move faster. Releasing joystick 28 removes electrical power from motors 37, causing assembly 10 to stop. Actuating right hand pushbutton 18 deflates air bag 40, releasing hitch 59, and allowing assembly 10 to be moved from device 100. In a similar manner, joystick 26 on first motion control unit 25 is used to move assembly 10 when it is not attached to a device 100.